

HighFinesse
The Standard of Accuracy

HighFinesse Tutorial

HighFinesse Analog PID Option (4 or 8 Channels): Laser Control

How to ...

... set up the HighFinesse Analog PID Option
(4 or 8 channels): Laser Control

The PCIe card will provide up to ± 10 V for controlling the lasers. This tutorial is intended to give you a brief overview of how to configure the HighFinesse laser control settings. The tutorial does not replace reading the manual. Make sure you have read and understood it (especially section 3.5) before you start the regulation. Setting voltage bounds incorrectly might cause damage to your laser.

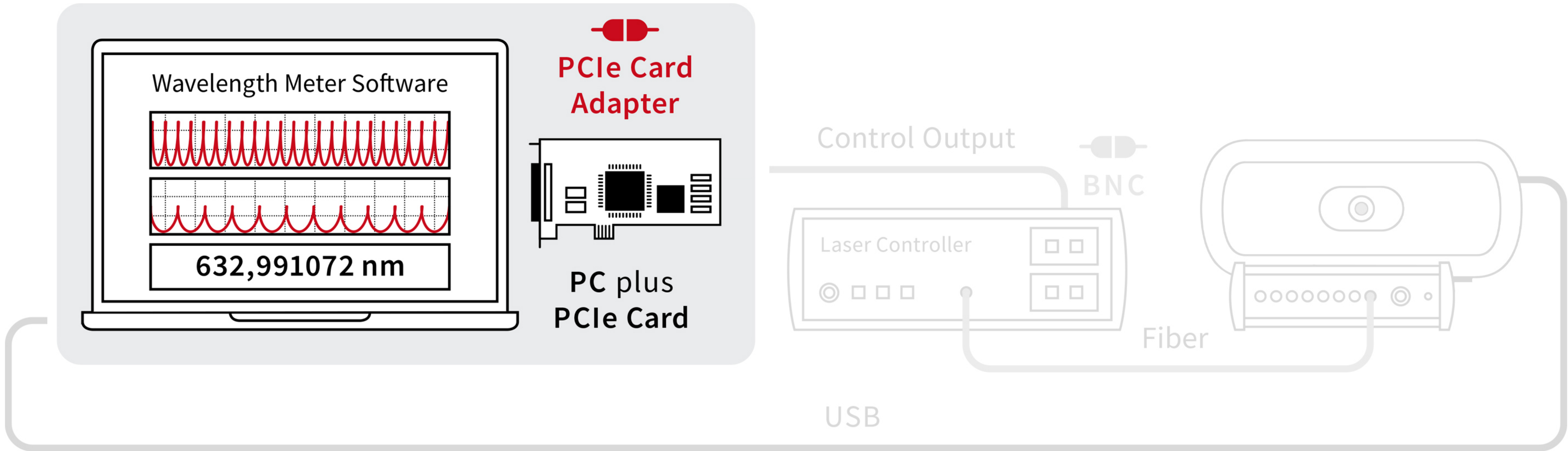
Here we assume that the laser is already successfully connected with a fiber to the wavelength meter. If you have any questions about that refer to the quickstart guide “HighFinesse Wavelength Meter”.

Quick Start Guide

HighFinesse Wavelength Meter

<https://www.highfinesse.com/en/support/quick-start-guide.html>





Insert the PCIe card to a suitable PCIe slot on your computer and **install the wavelength meter software** (which installs all drivers automatically).



The screenshot displays the 'Laser Control' software interface. On the left, a 'Settings' menu is open, with 'Laser Control Settings ...' highlighted. The main window shows a 'Regulation & Sensitivity' section with a 'Bounds' tab selected. Below this, a graph plots intensity (632.99107) against time (t[s]).

Laser Control

☐ Regulation signal active Port 1 2 3 4 5 6 7 8

Modify | Altering sensitivity | Errorsignals | Calibration
 Reference | **Regulation & Sensitivity** | Bounds | Various

Signal bounds [mV]

Minimum Maximum

☒ Adjust reference midway (0.0 mV)
☐ Adjust reference at mV

Behaviour on exceeding bounds

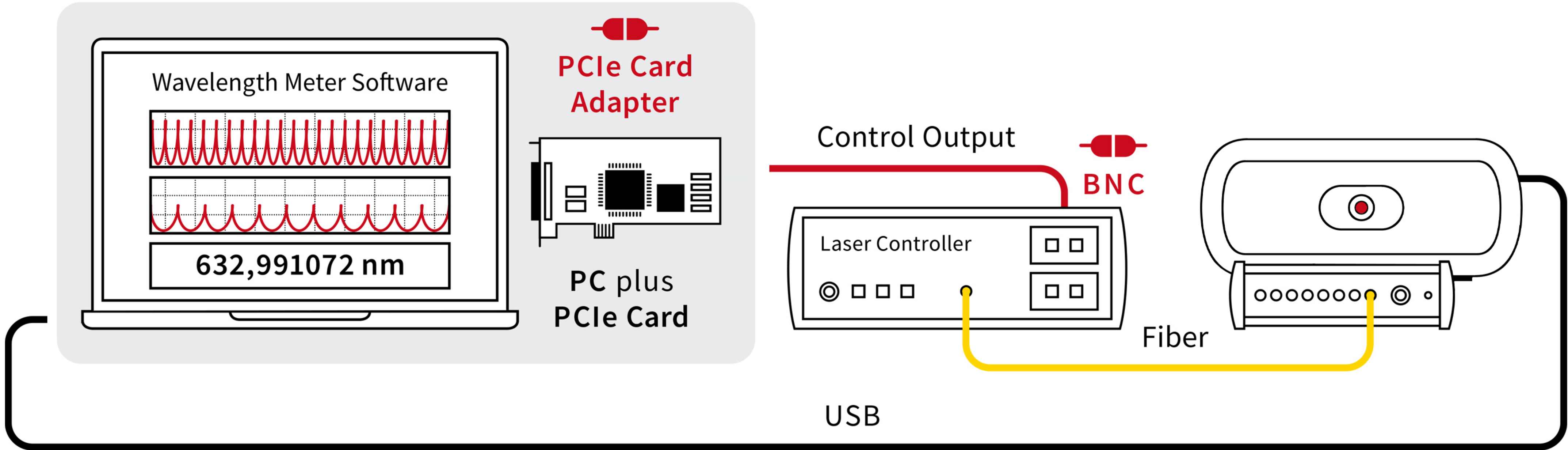
☒ Only cut at signal bounds
☐ Output errorvalue [mV]
 at min. at max.

☒ Clear integral history

☐ Maximum shot-per-shot change [mV]
 ☒ allow towards zero
☐ drive immediately

Move to the **frame bounds** to enter them correctly.

4

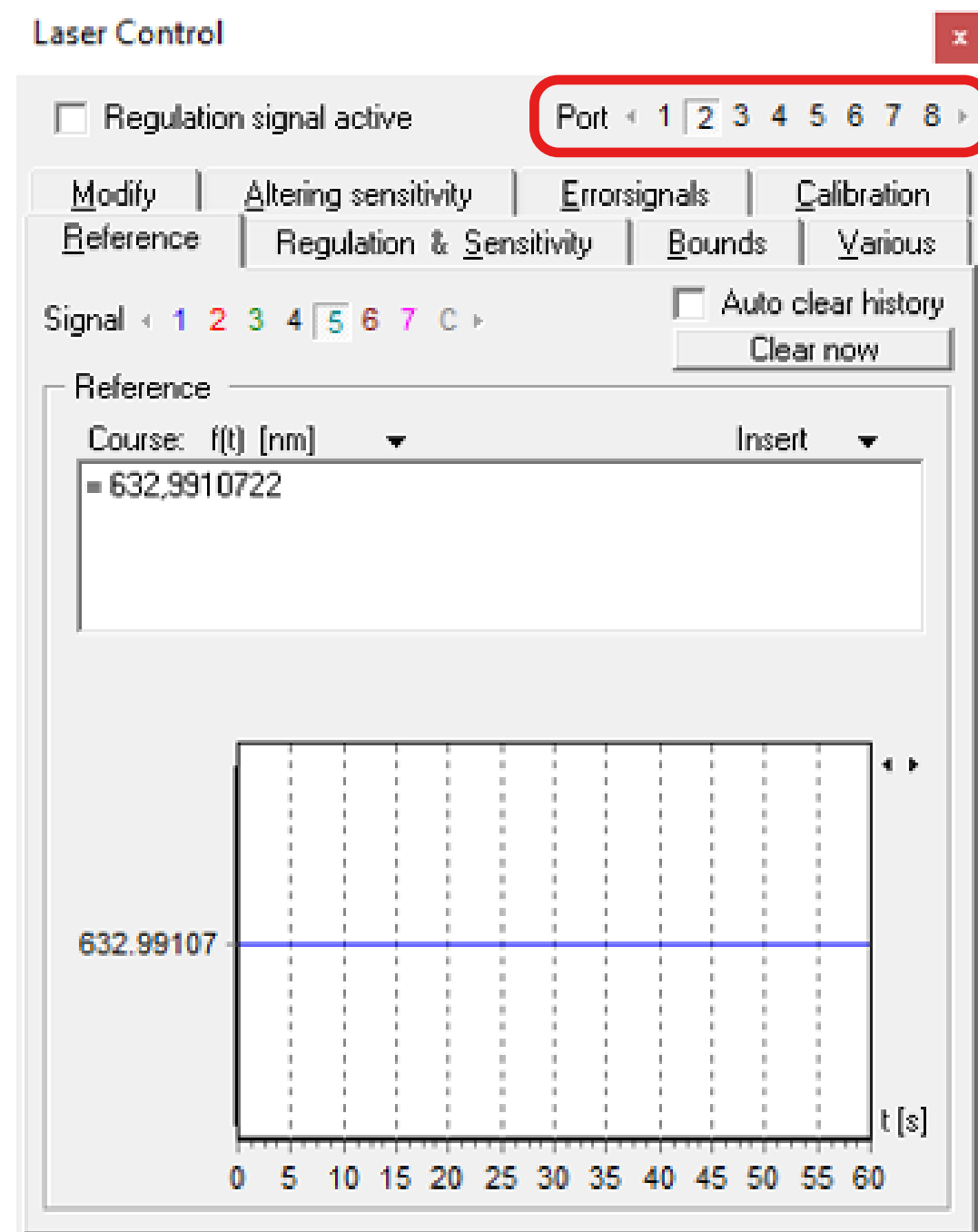


Connect the voltage output of the PCIe card to the input at the laser using the adapter cable (minimum impedance at the laser input 10 kOhm).



5

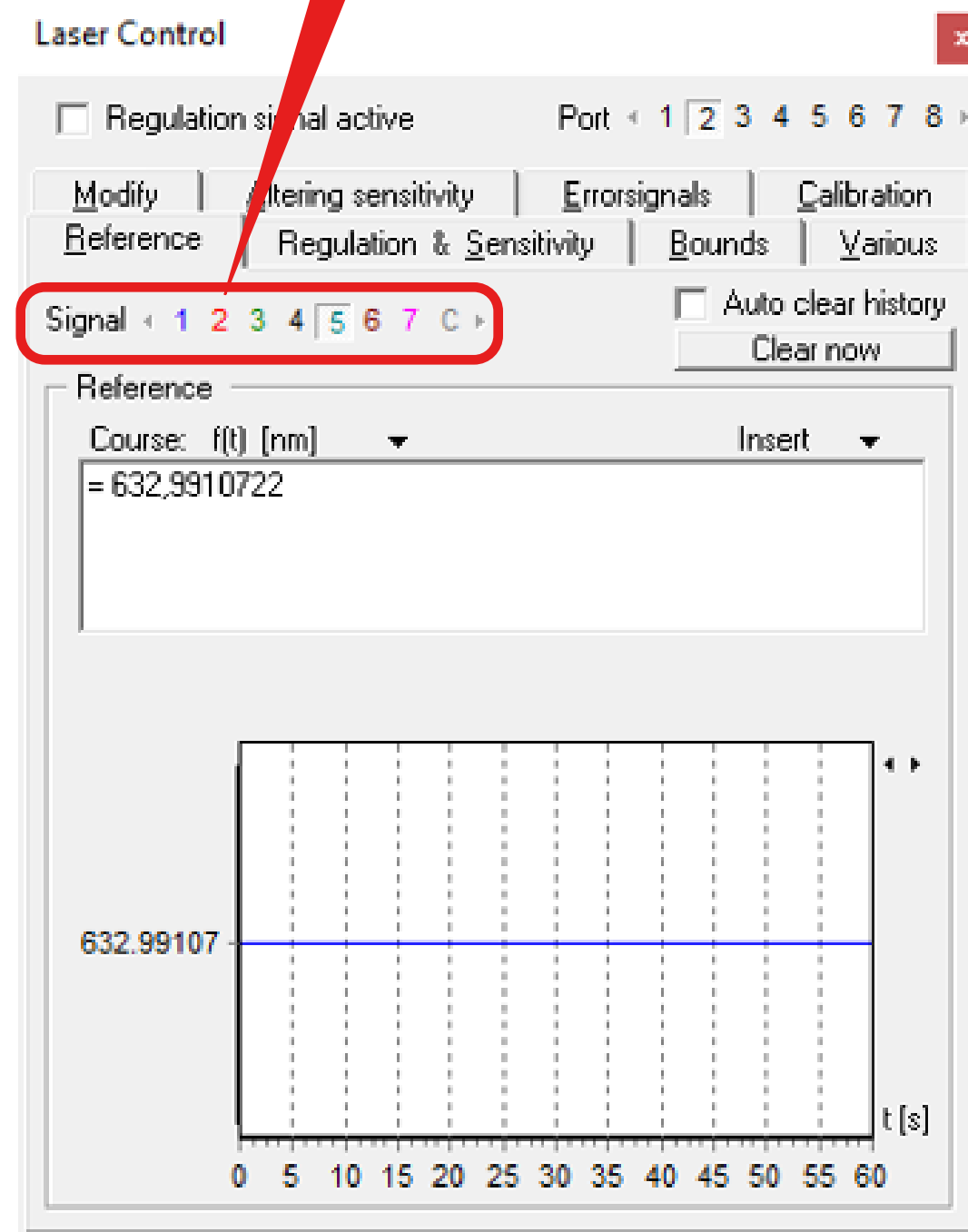
Using multiple channels simultaneously



Choose the port where the voltage will be put out by clicking on the **black** numbers.

5a

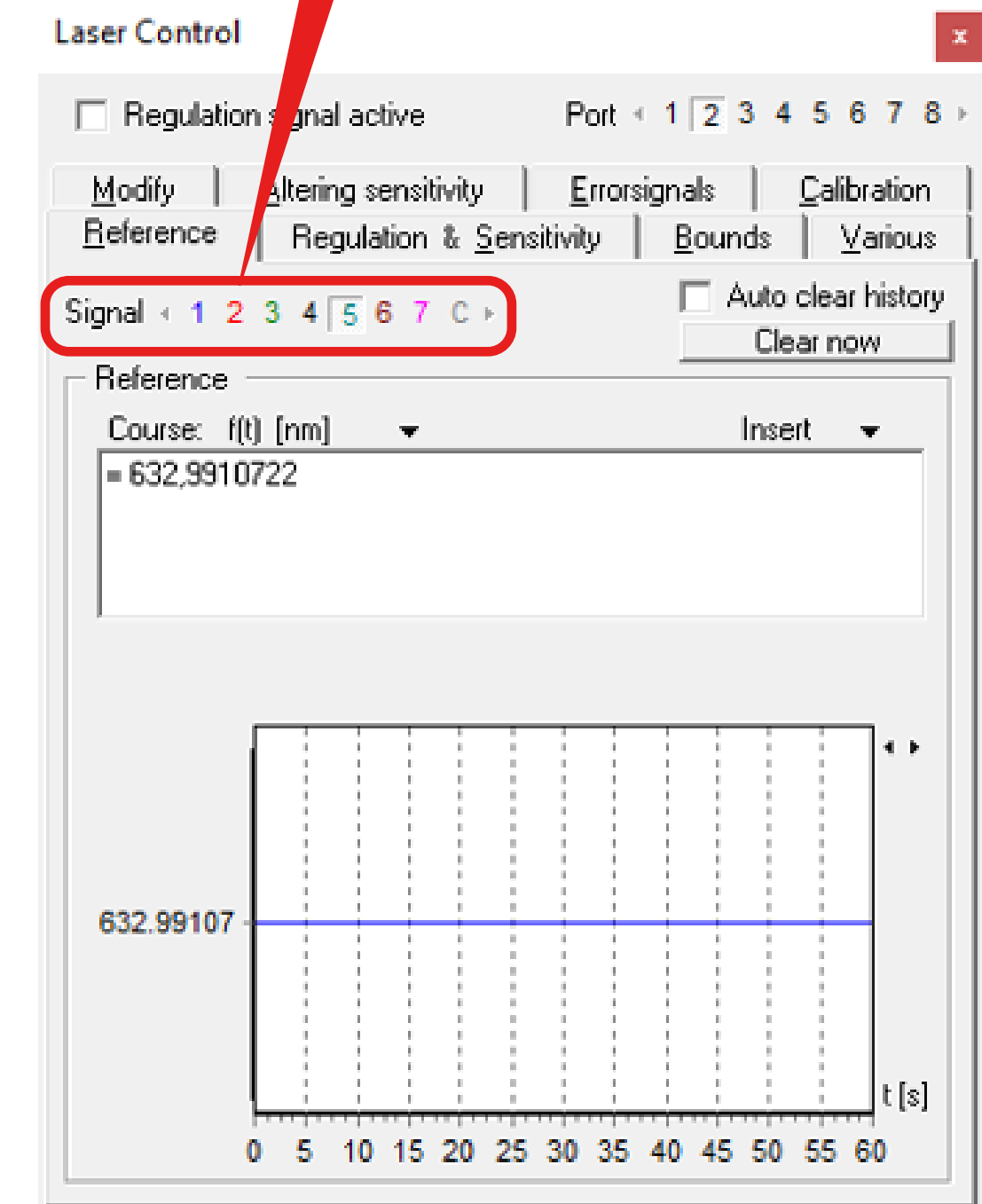
**Click to
assign ...**



Then click on one of the colored numbers to assign the switch signal to the port.

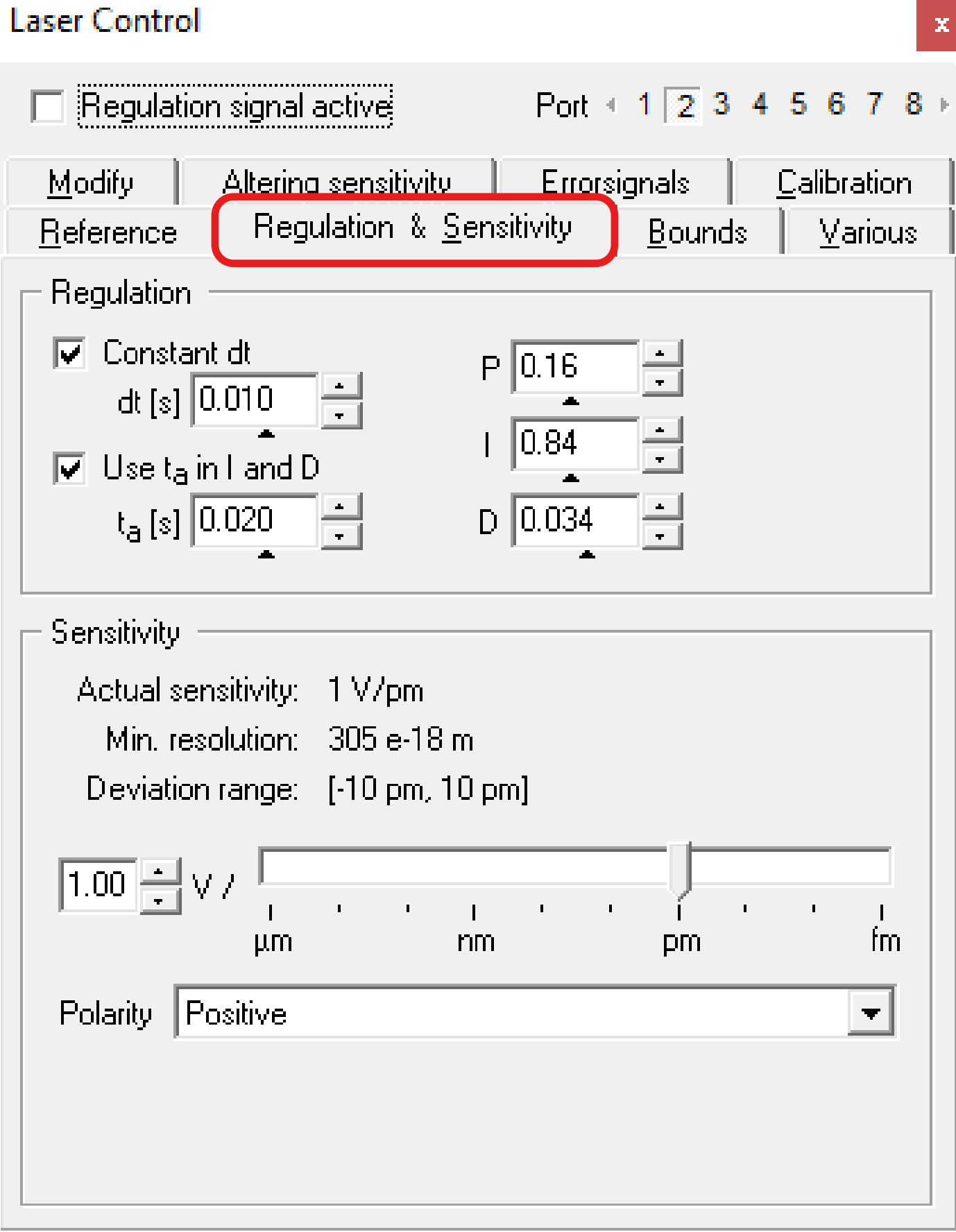
5b

Click again to unassign ...

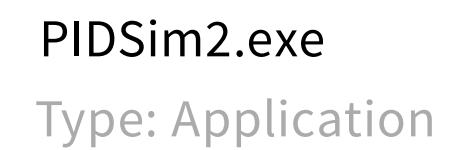


You can **unassign** it by clicking on the **same number again**. In the example the Switch signal 5 is assigned to port 2.

Use the **PIDSim2 Tool** to simulate good starting parameters.



Start ...

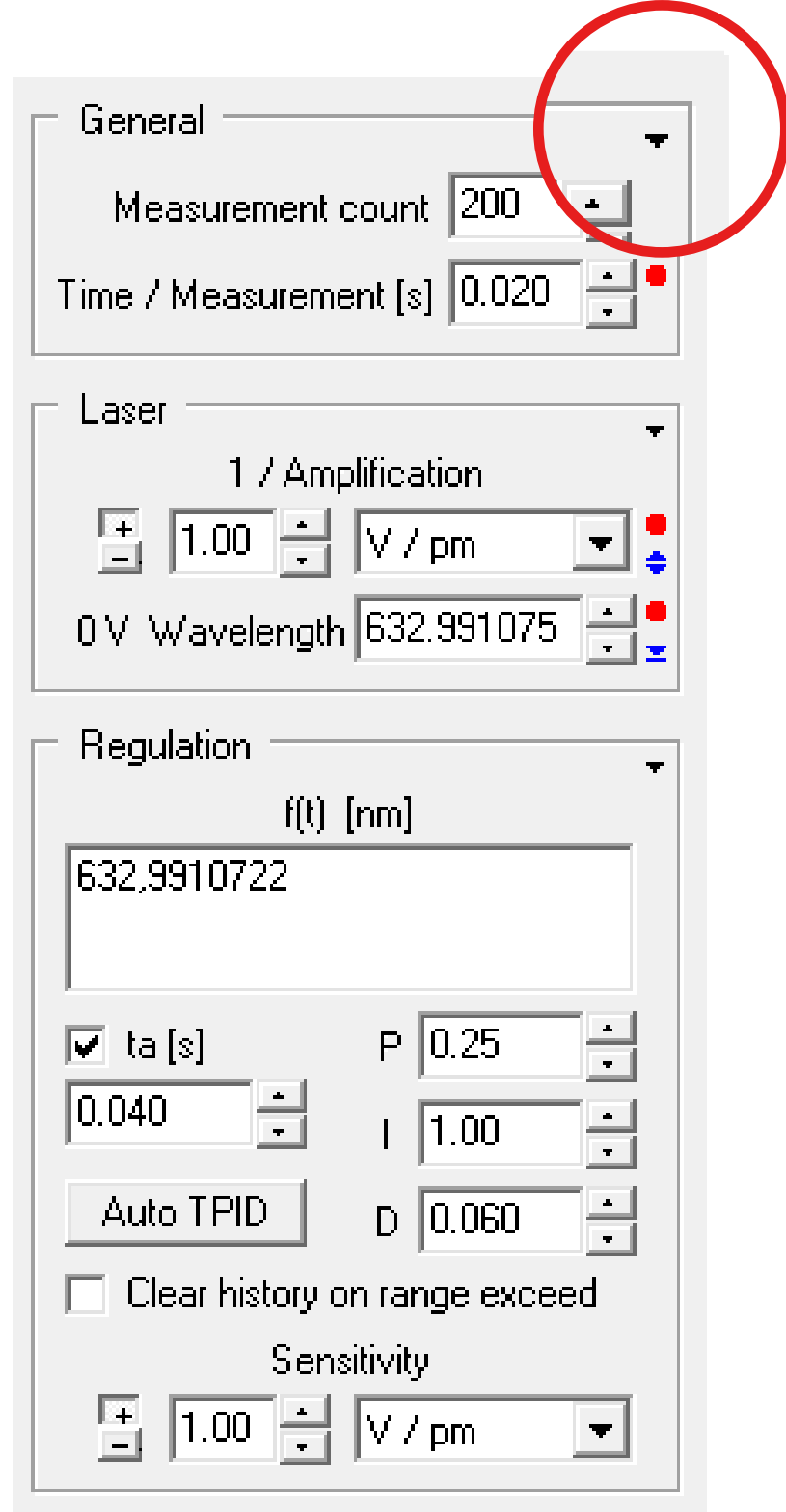


Installation Path of the Wavelength Meter Software

\Tools
\PIDSim2.exe

... and make sure you can measure.

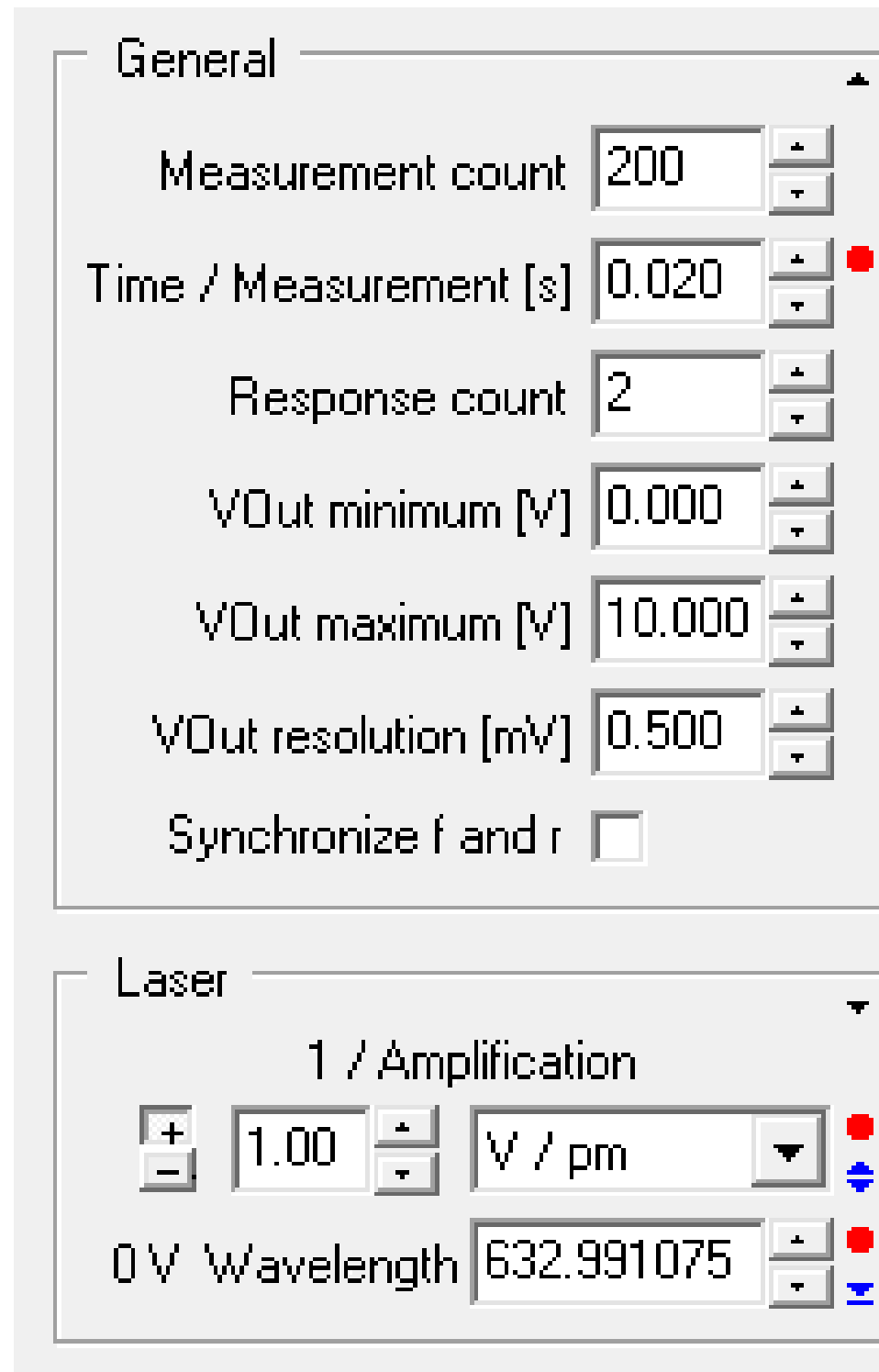
8



Clicking on the **small black triangle** will enable more settings.

8a

PIDSim2 Settings



Now you can **make your settings**
for simulation.

Measurement count:

number of points in the simulation.

Time/Masurement [s]:

get this live from the wavelength meter by clicking on the red dot and confirm by clicking on the checkmark.

Response Count:

2 for single channel, 1 for multichannel measurements.

Set the **minimum and maximum output** according to your system (voltage bounds set in 1.).

Set the **resolution** to obtain a realistic simulation of your system.

Regulation

$f(t)$ [nm]

= 632,9910722

☒ t_a [s] P 0.25

0.040 I 1.00

Auto TPID D 0.060

☐ Clear history on range exceed

Sensitivity

+ 1.00 V / nm

Synchronize WLM

Connection with WLM

In which direction shall be synchronized first?

WLM --> PIDSim

PIDSim2 --> WLM

Choose ...

Choose to **synchronize** the
PIDSim2 in the **section regulation**.

You can **alternatively also transfer all settings** you have made from the wavelength meter to the PIDsim2 tool.

Regulation

$f(t)$ [nm]

= 632,9910722

☒ ta [s] 0.040

P 0.20

I 1.00

D 0.060

Auto TPID

☐ Clear history on range exceed

Sensitivity 1.00

Port 1

Release WLM

10

Click on the blue triangles to enter the bounds **10a** (range should be smaller or equal to the bounds in 1.) and number of collection points used for calculation.

Then click on the red dot **10b** to automatically **determine the sensitivity**. Once this is determined transfer the result to the frame “Regulation” and enter it as the “Sensitivity” of the laser.

Caution: this will vary the output voltage, so a safe choice for the bounds is important.

Amplification settings

Collection points per cycle

Upper voltage border [mV]

Lower voltage border [mV]

Laser

1 / Amplification

1.00 V / pm

Wavelength 632.991075

Perturbation [pm]

0

Noise [pm] 0.000

Sudden hops [pm] 0.000

10b Click to determine the sensitivity ...

10a Click to enter the bounds ...

11

Reference Voltage

Reference Voltage [mV] 1000

Laser

1 / Amplification

1.00 V / pm

0 V Wavelength 632.991075

Perturbation [pm]

0

Noise [pm] 0.000

Sudden hops [pm] 0.000

11c Get the current wavelength

11a Click to enter the current voltage ...

Click on the **blue triangle** **11a**.

Enter the **current voltage** **11b**.

Get the corresponding wavelength by clicking on the red dot **11c**.

Regulation ▲

$f(t)$ [nm]

= 632,9910722

☒ t_a [s]

0.040

▲
▼

P

0.25

▲
▼

I

1.00

▲
▼

D

0.060

▲
▼

Auto TPID

☐ Clear history on range exceed

Sensitivity

+
-

1.00

▲
▼

V / pm

▼

Synchronize WLM

● ● ● ● ● ● ● ● ● ● ●

Regulation ▲

$f(t)$ [nm]

= 632,9910722

☒ t_a [s]

P ▲▼

▲▼

I ▲▼

D ▲▼

☐ Clear history on range exceed

Sensitivity

▲▼

▼

Regulation

$f(t)$ [nm²]
= 632,9910722

☒ t_a [s] 0.040

P 0.25

I 1.00

D 0.060

Auto TPID

☐ Clear history on range exceed

Sensitivity

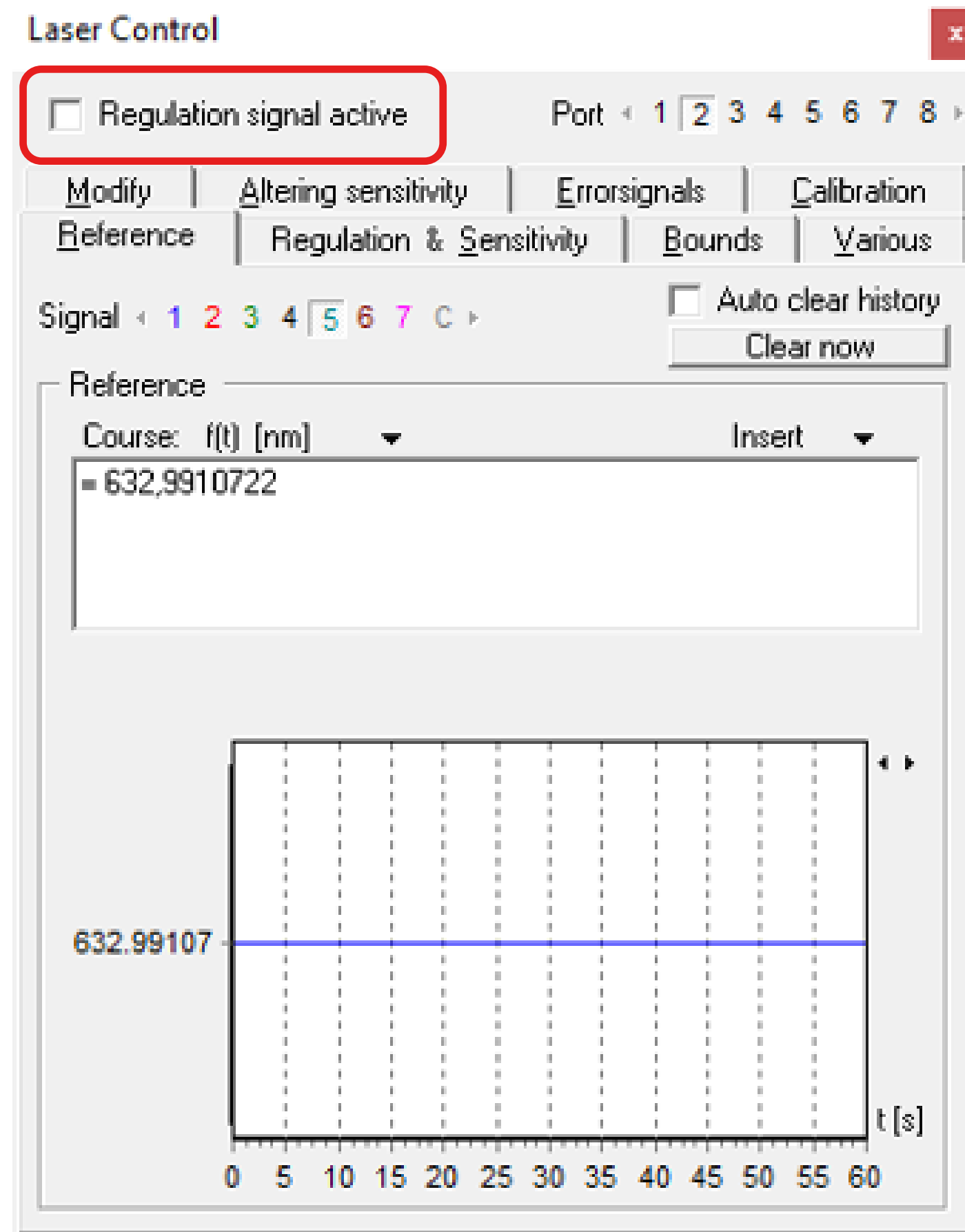
+ 1.00 - V / pm

Synchronize WLM

Click to delete the PID parameter

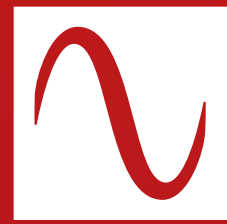
Click to determine the PID parameters.

Press **“Auto TPID”** to determine the PID parameters. **Finally, you can close the PIDSim2.** Now the system should be ready for a test.



For this **start the Regulation.**

You can **optimize the regulation** further by using the LongTerm application and minimizing possible unwanted effects by altering the PID parameters.



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