

HighFinesse  
The Standard of Accuracy

HighFinesse Tutorial

# HighFinesse Digital PID Option: Laser Control

How to ...

## ... set up the HighFinesse Digital PID Option: Laser Control

This option can be used with TOPTICA lasers controlled by a DLC pro only. This quickstart guide is intended to give you a brief overview of how to configure the HighFinesse laser control settings. The guide does not replace reading the manual. Make sure you have read and understood it (especially section 3.5) before you start the regulation. Setting voltage bounds incorrectly might cause damage to your laser.

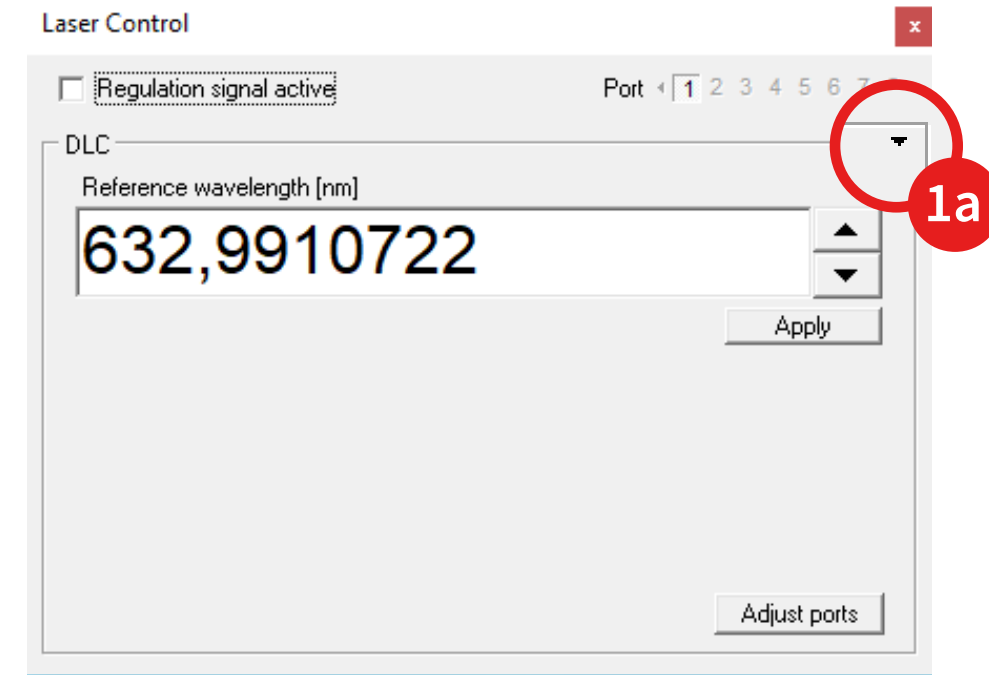
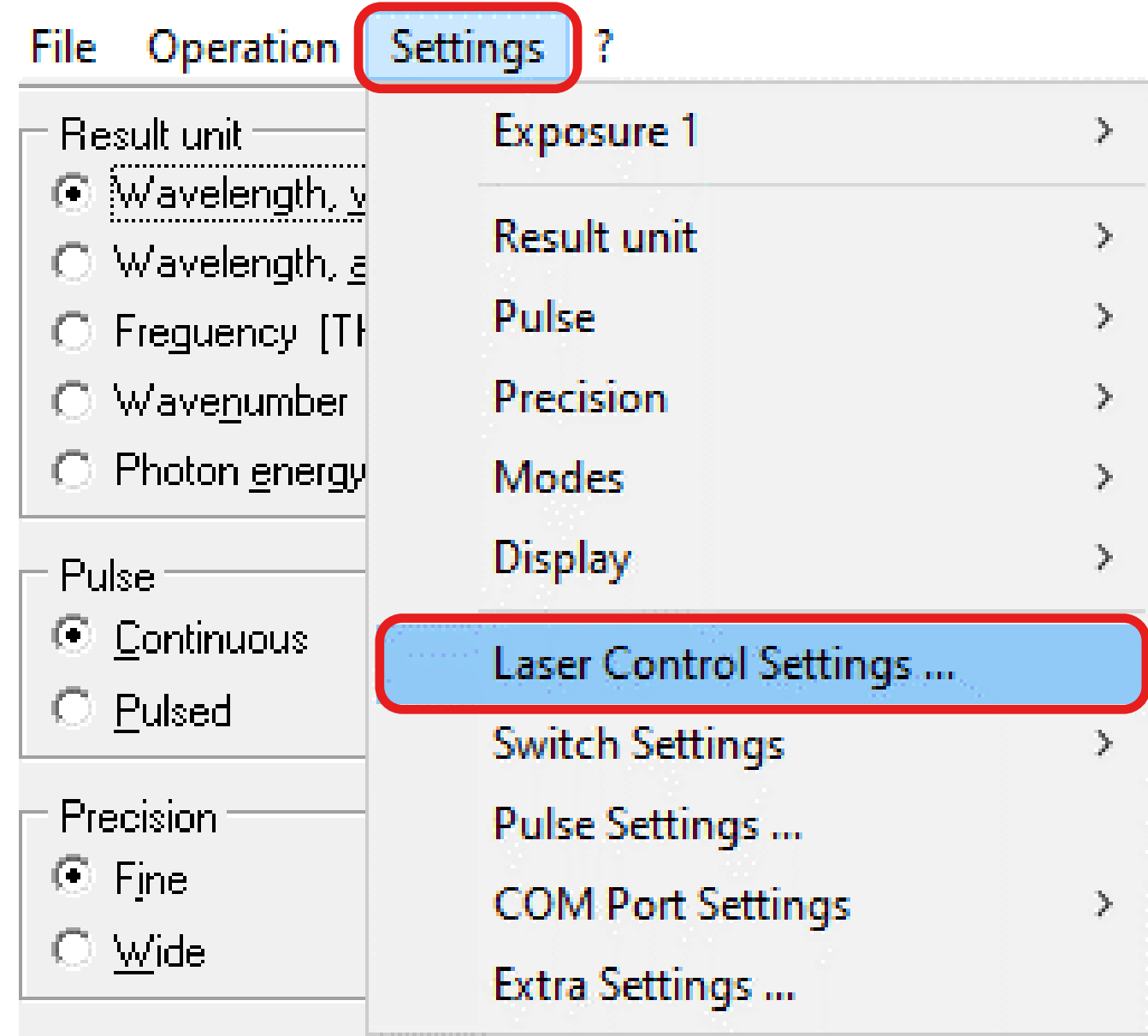
Here we assume that the laser is already successfully connected with a fiber to the wavelength meter. If you have any questions about that refer to the quickstart guide “HighFinesse Wavelength Meter”

Quick Start Guide  
HighFinesse Wavelength Meter

[https://www.highfinesse.com  
/en  
/support  
/quick-start-guide.html](https://www.highfinesse.com/en/support/quick-start-guide.html)

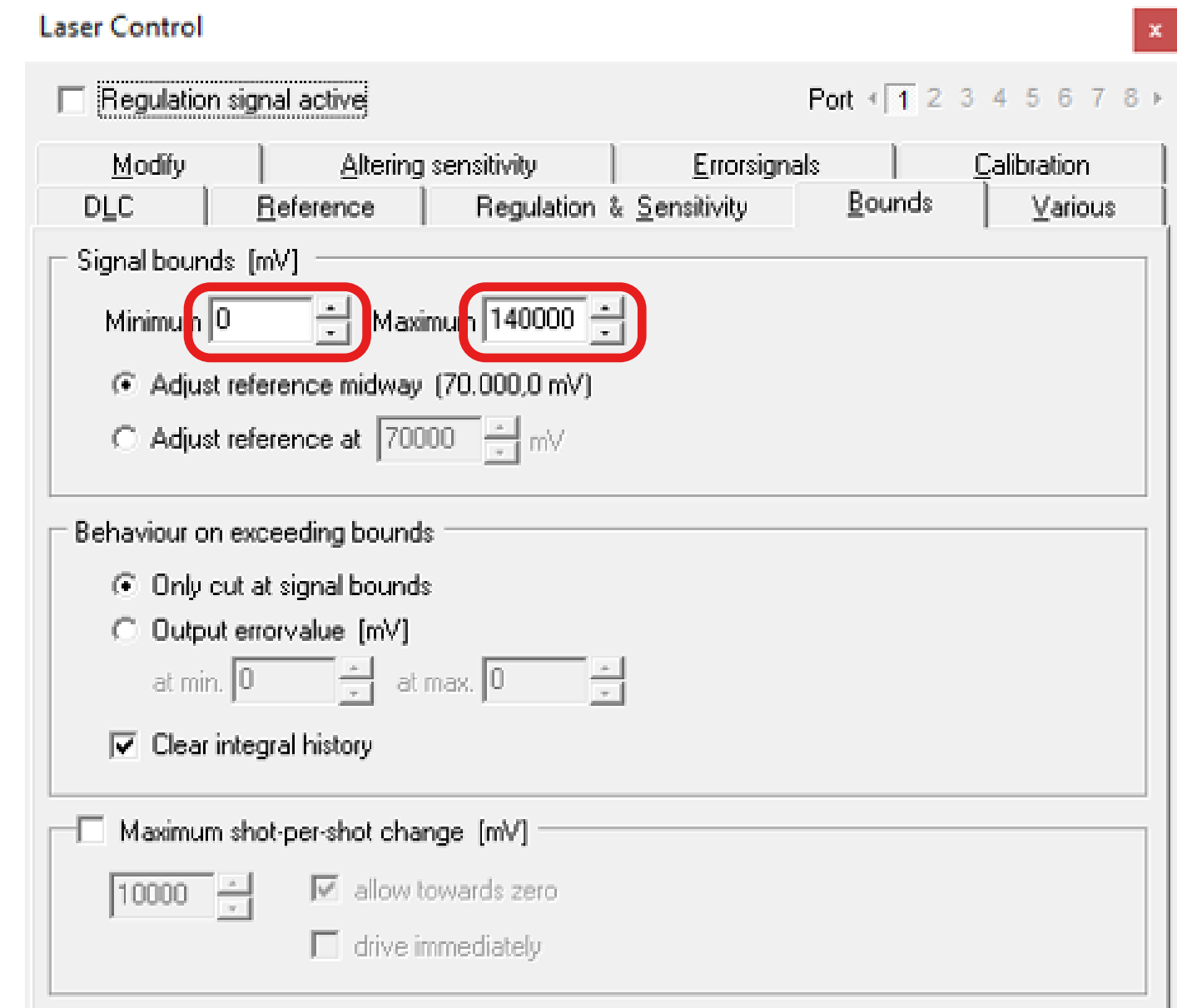


1



Start the software and set the voltage bounds in the Laser Control Menu such that you can exclude a damage to your laser and make sure the output range is suitable (e.g. as defined by a mode-hope-free scanning range).

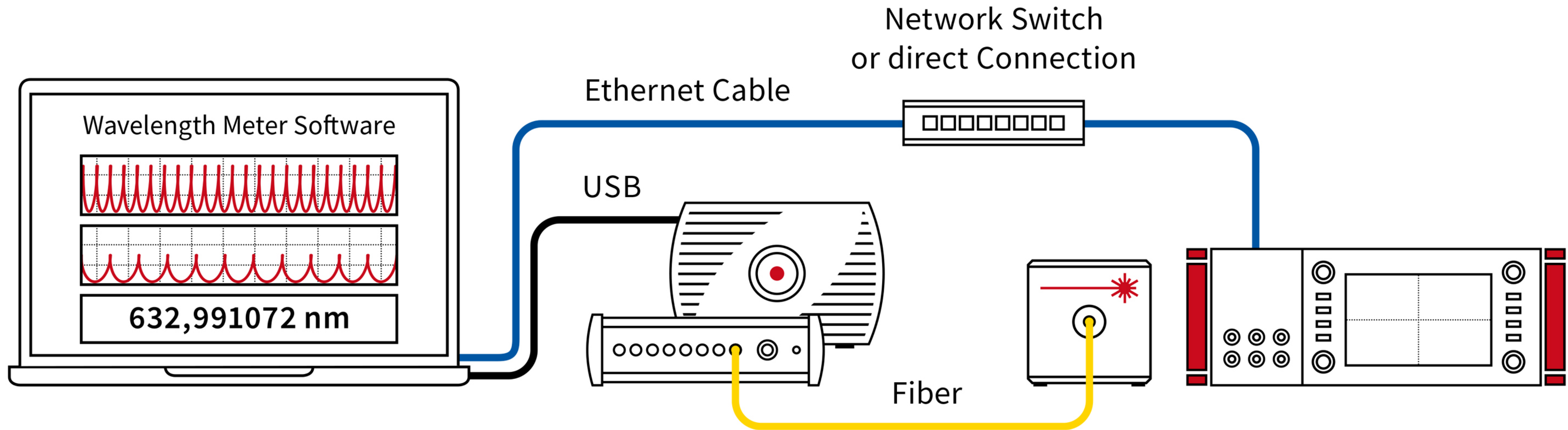
2



Click on the black triangle **1a** to obtain more settings. Move to the frame bounds to enter the correct bounds.



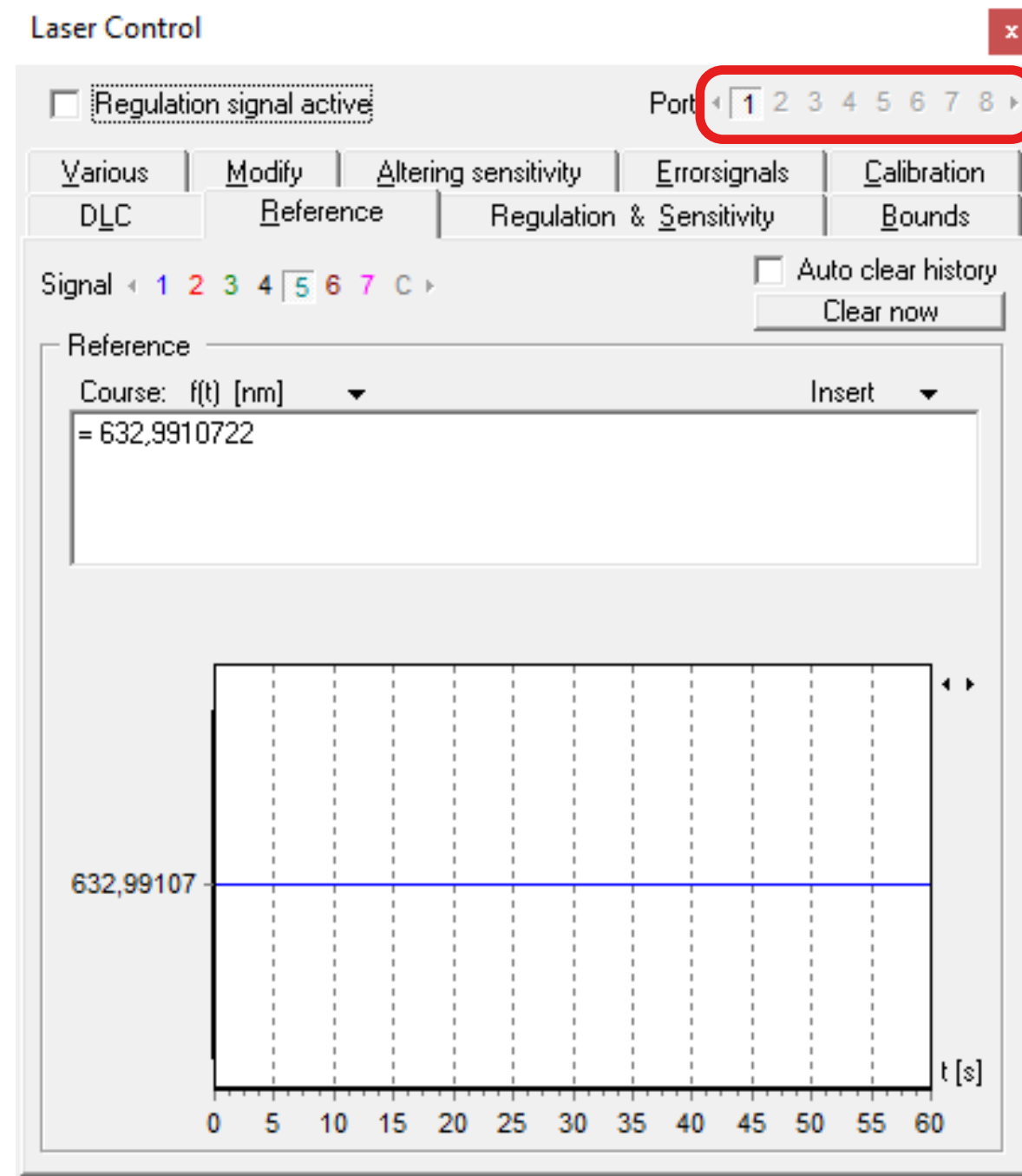
3



Connect the DLC pro Controller and the computer running the wavemeter software to the same network (UDP has to be allowed for automatic recognition).

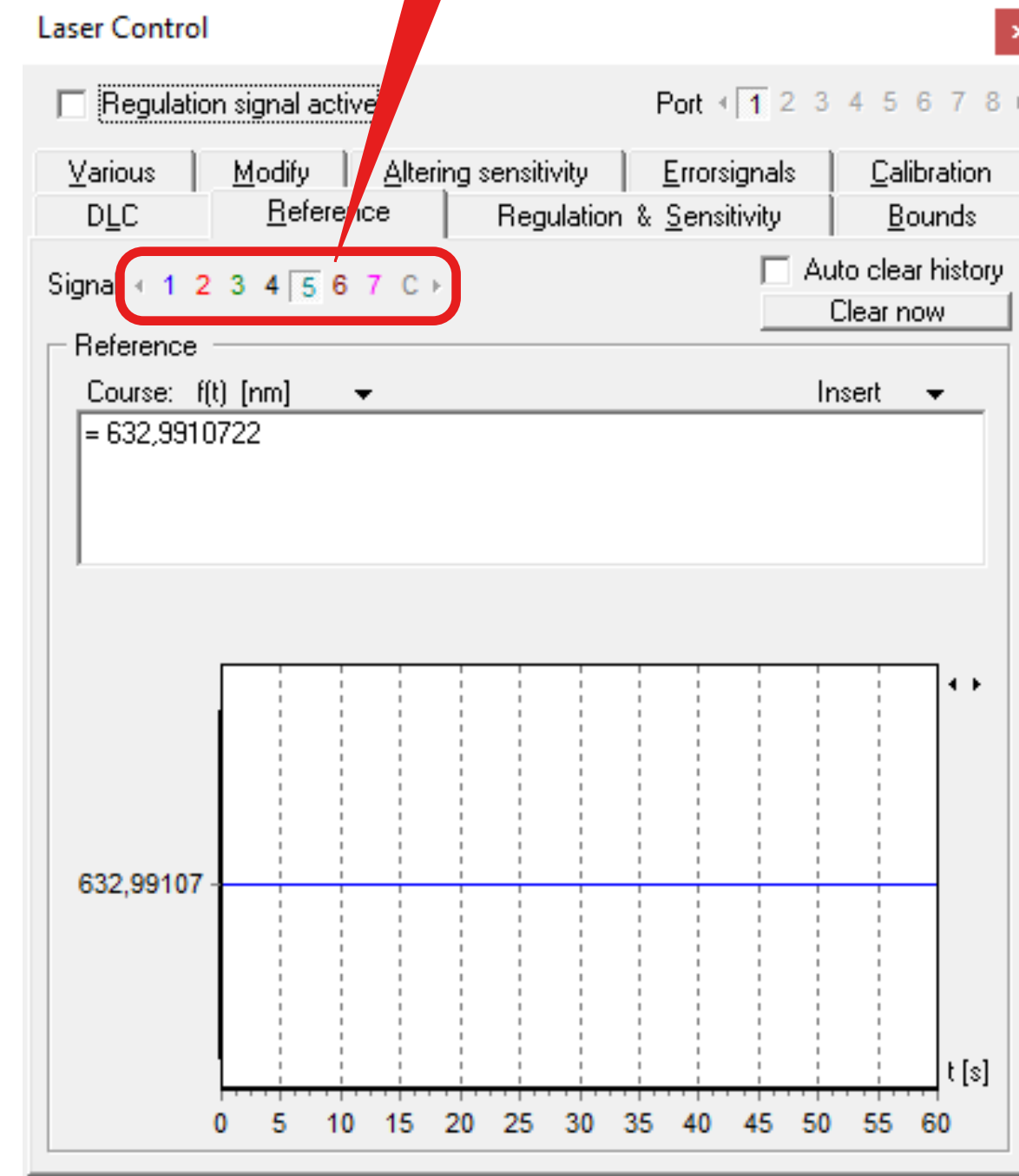
In restrictive network it might be necessary to specify the IP address and the port of the DLC pro Controller (Standard port: 1998) in the “Adjust ports” menu → “Additional IPs”.

#### 4 Using multiple channels simultaneously



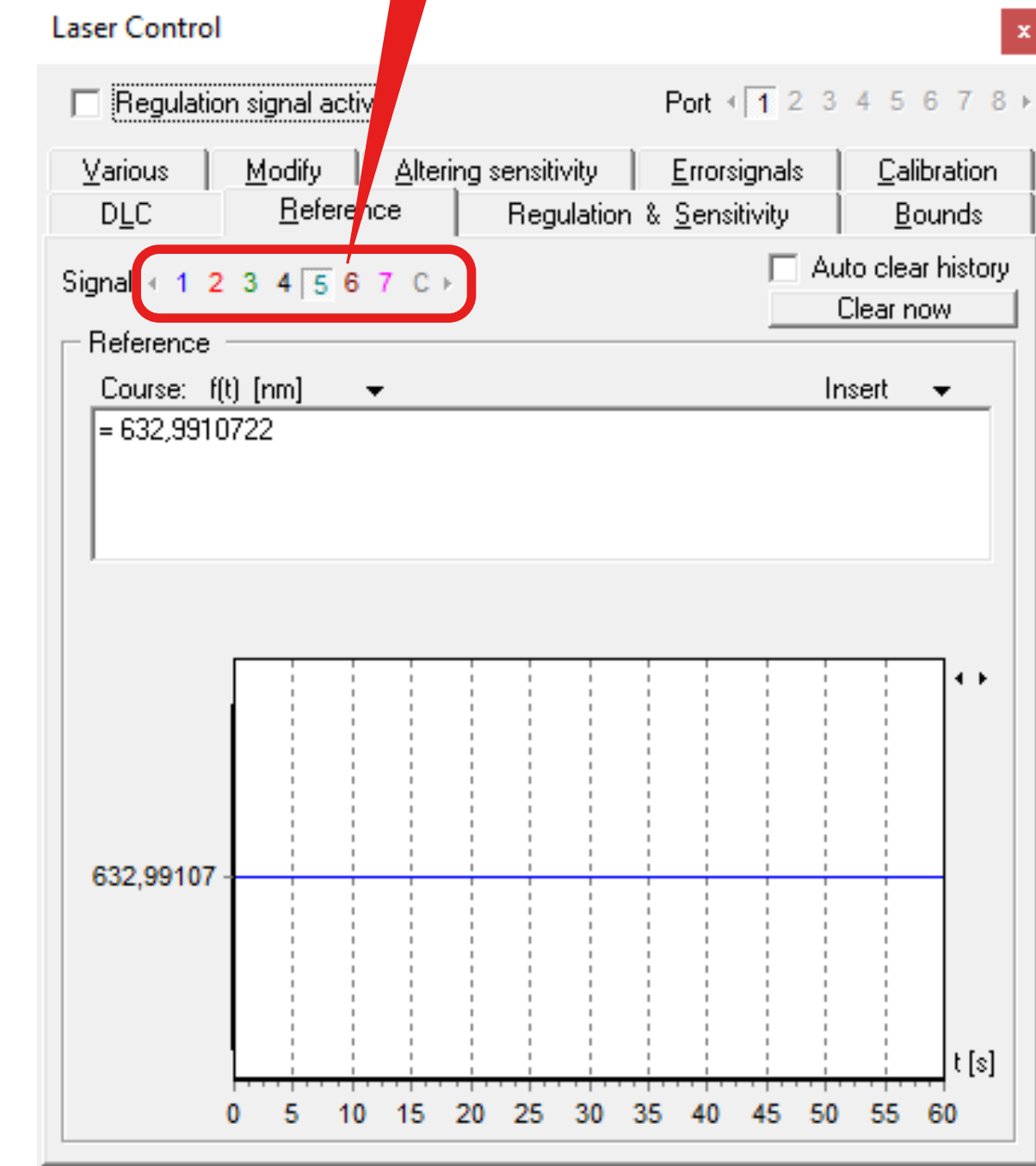
Choose the port where the digital signal will be put out by clicking on the black numbers.

#### 4a Click to assign ...



Then click on one of the colored numbers to assign the switch signal to the port.

#### 4b Click again to unassign ...



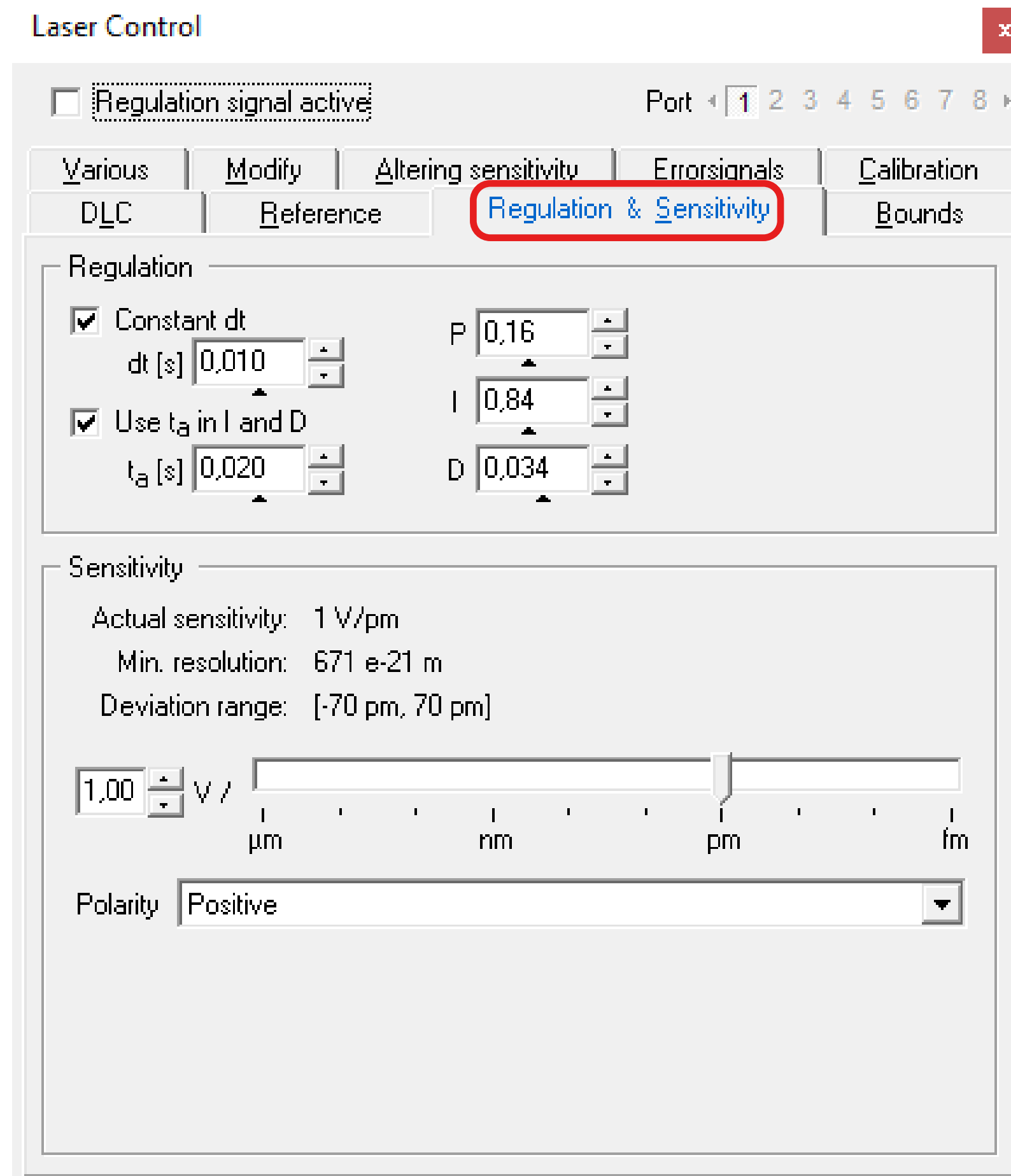
You can unassign it by clicking on the same number again. In the example the Switch signal 5 is assigned to port 1.



5

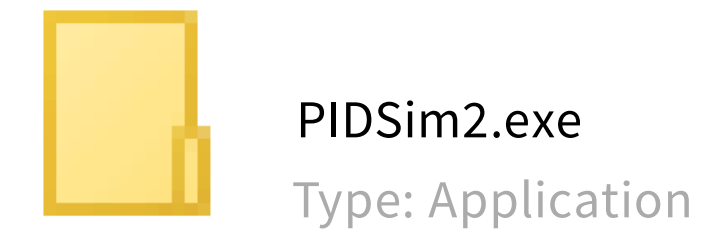
Use the **PIDSim2 Tool** to simulate good starting parameters.

Alternatively, you can set PID parameters manually in the laser control settings/frame: **“Regulation & Sensitivity”**.



6

Start ...



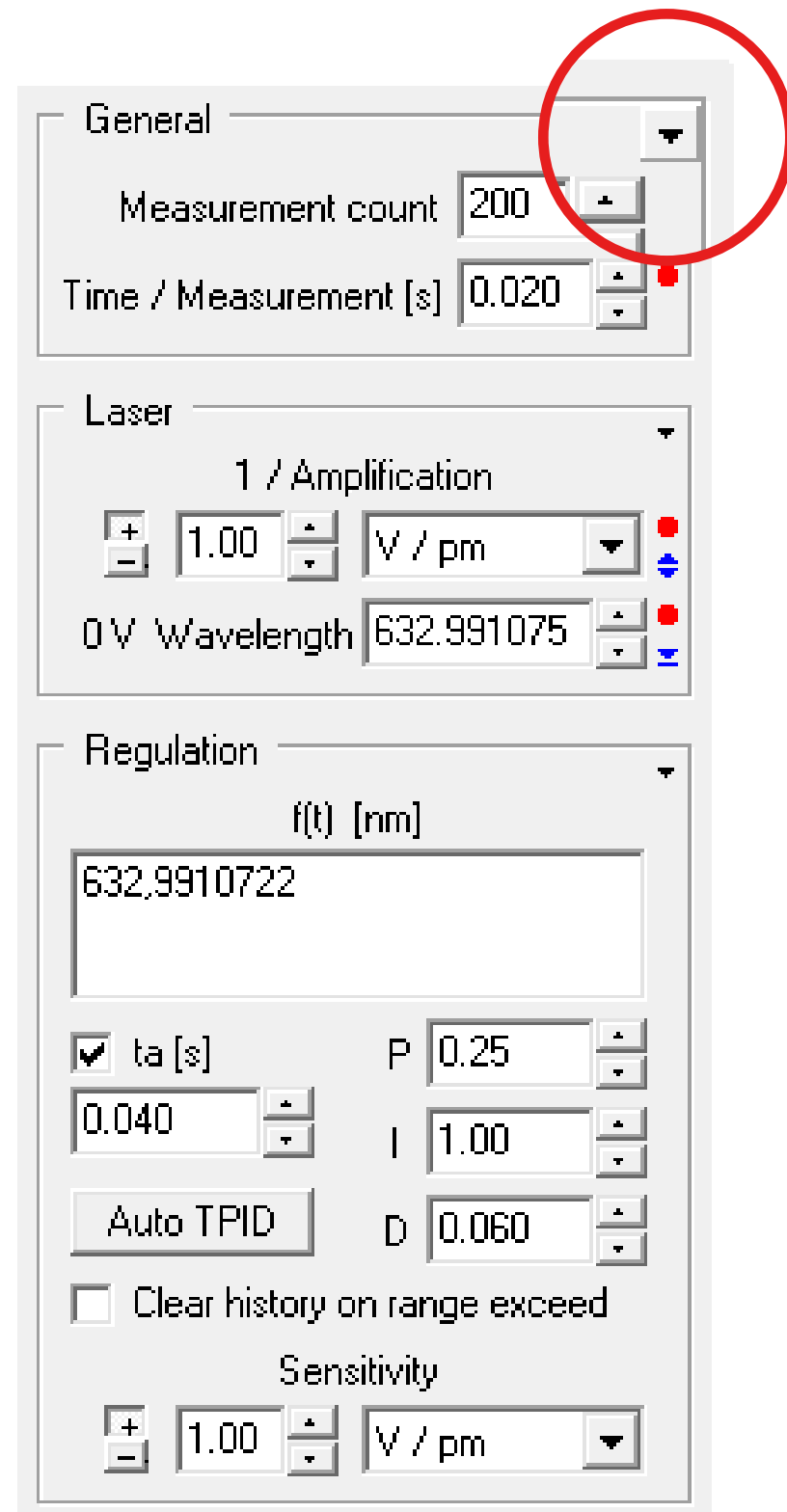
Start the **PIDSim2 application** located in the path ...

**Installation Path of the wavemeter Software**  
**\Tools**  
**\PIDSim2.exe**

... and make sure you can measure.



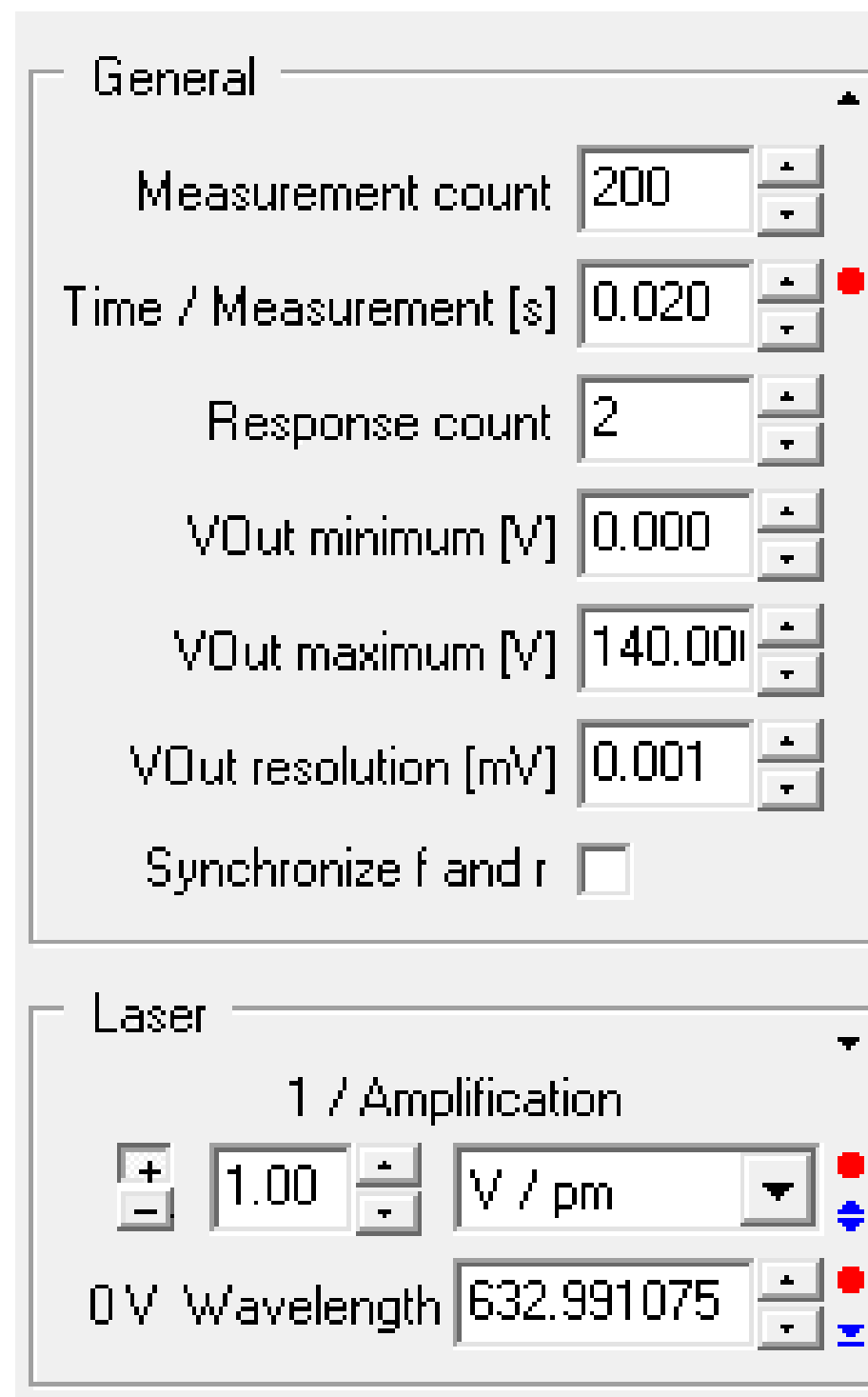
7



Clicking on the **small black triangle** will enable more settings.



7a PIDSim2 Settings



Now you can **make your settings** for simulation.

**Measurement count:**  
number of points in the simulation.

**Time/Measurement [s]:**  
get this live from the wavemeter by clicking on the red dot and confirm by clicking on the checkmark.

**Response Count:**  
2 for single channel, 1 for multichannel measurements.

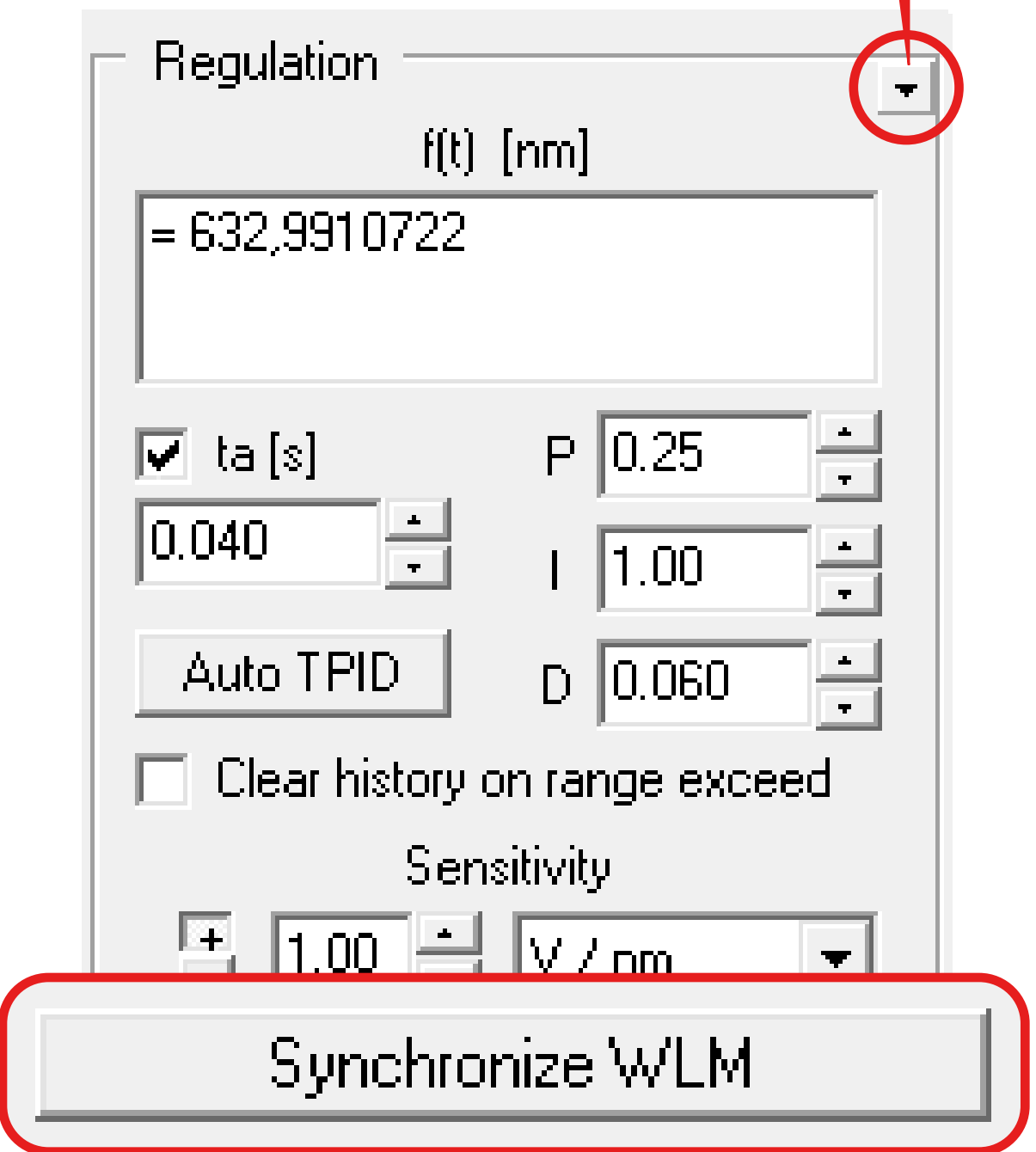
Set the **minimum and maximum output** according to your system (voltage bounds set in 1.).

Set the **resolution** to obtain a realistic simulation of your system.



8

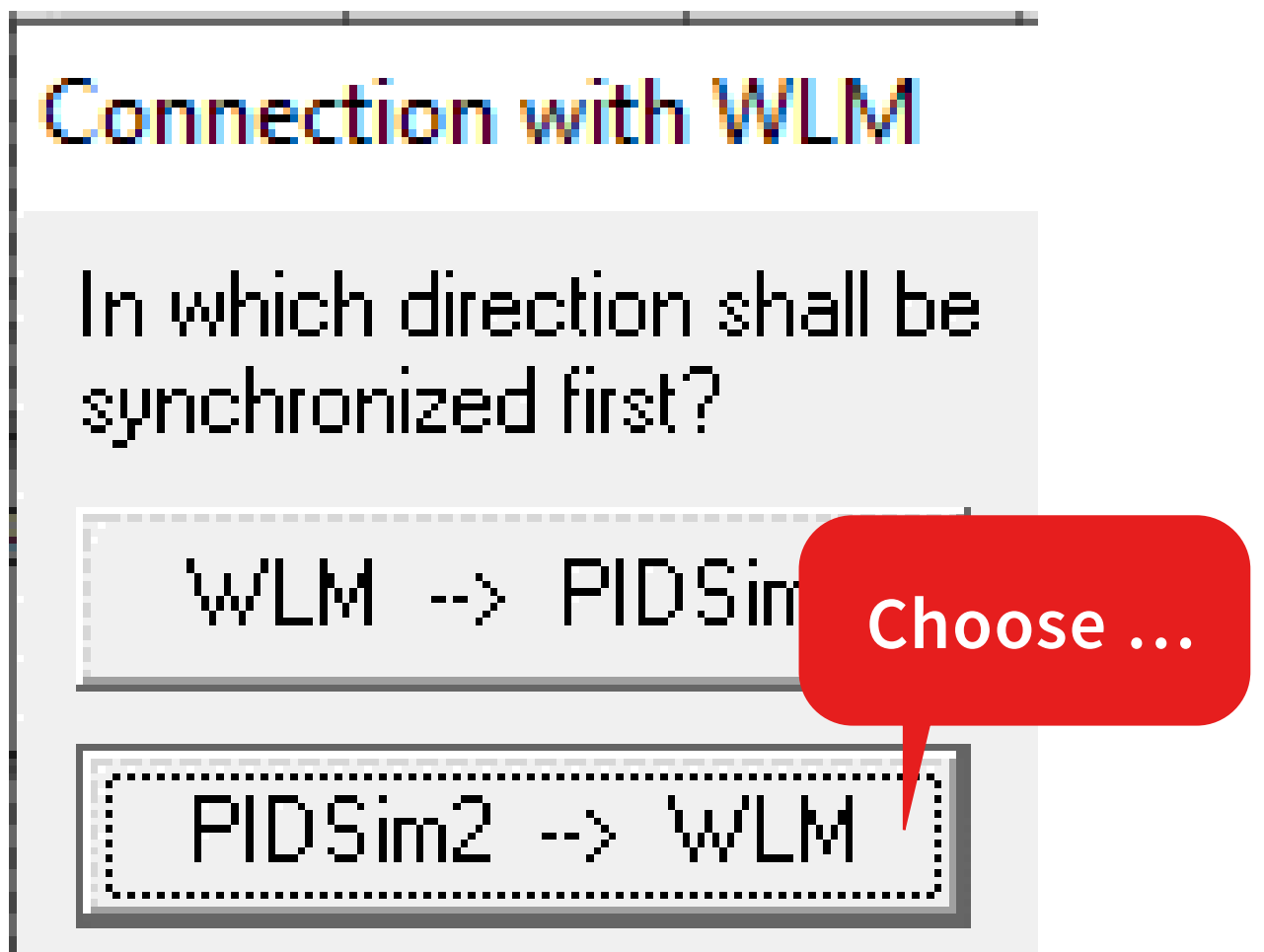
Show more settings ...



The tool can be used as a **pure simulation** tool or **synchronized to the wavelength meter software** running in parallel.



8a

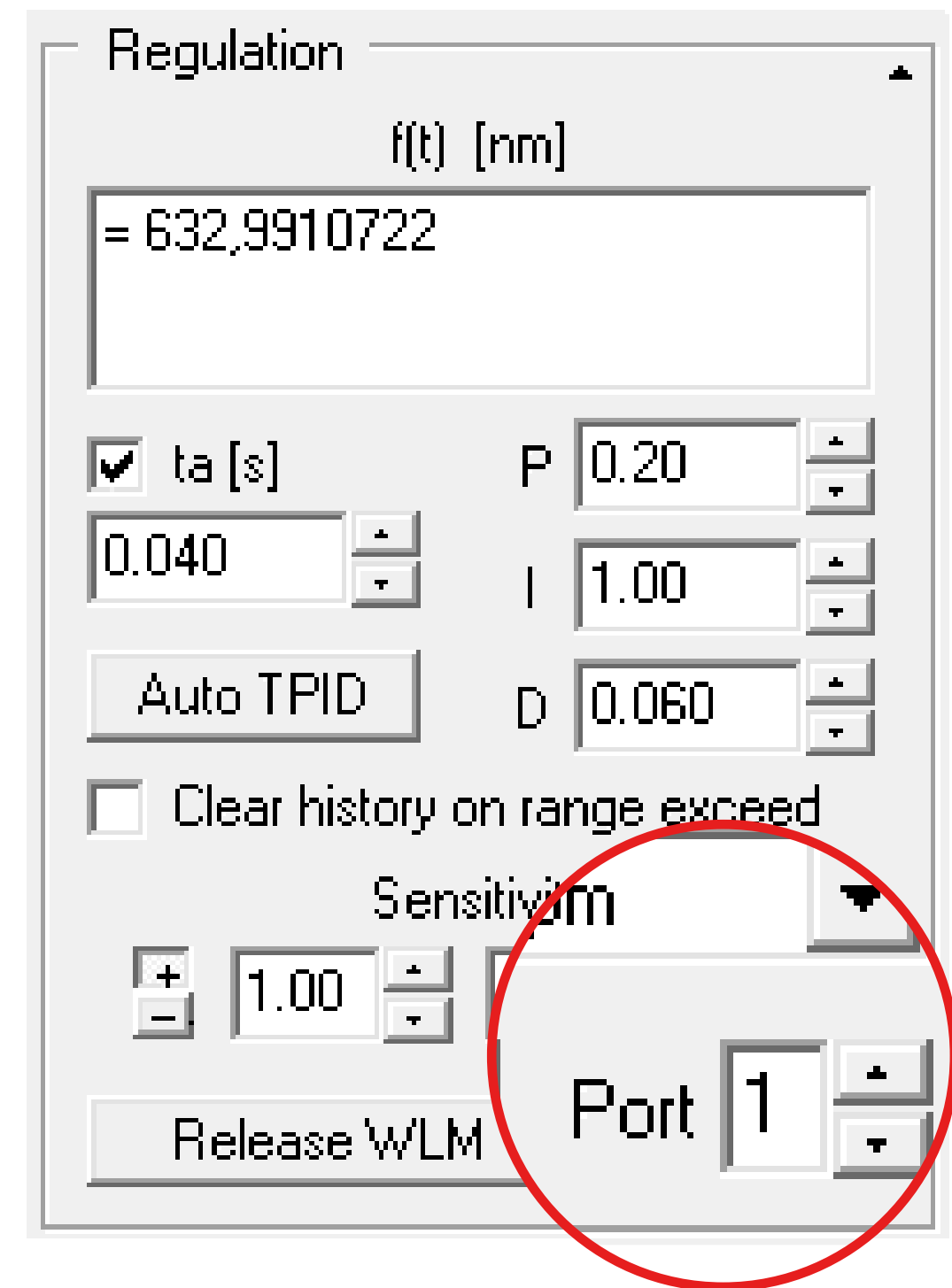


Choose to **synchronize the PIDSim2** in the section regulation.

Choose **PIDSim --> WLM**.

You can **alternatively also transfer all settings** you have made from the wavemeter to the PIDsim2 tool.

8b



After that **set the port** that you would like to adjust.

9

Click on the blue triangles to enter the bounds **9a** (range should be smaller or equal to the bounds in 1.) and number of collection points used for calculation.

Then click on the red dot **9b** to automatically determine the sensitivity. Once this is determined transfer the result to the frame “Regulation” and enter it as the “Sensitivity” of the laser.

**Caution:** this will vary the output voltage, so a safe choice for the bounds is important.

Amplification settings x

Collection points per cycle	<input type="text" value="900"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>
Upper voltage border [mV]	<input type="text" value="1250"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>
Lower voltage border [mV]	<input type="text" value="-1250"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>

Laser

1 / Amplification

<input type="button" value="+"/> <input type="button" value="-"/>	<input type="text" value="1.00"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>	<input type="text" value="V / pm"/>	<input type="button" value="⬇"/> <input type="button" value="⬆"/>
0 V Wavelength	<input type="text" value="632.991075"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>	<input type="button" value="⬇"/> <input type="button" value="⬆"/>	

Perturbation [pm]

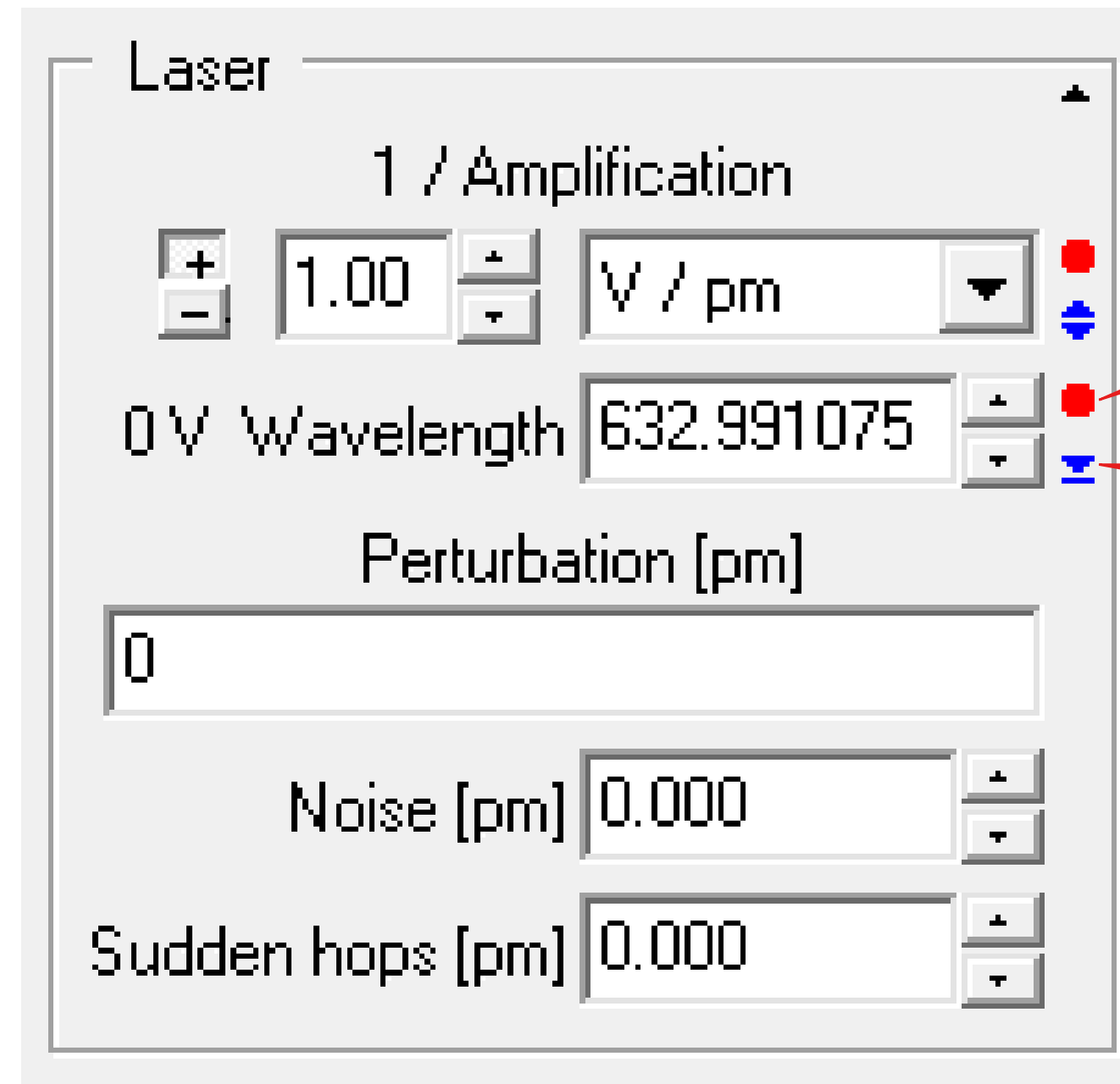
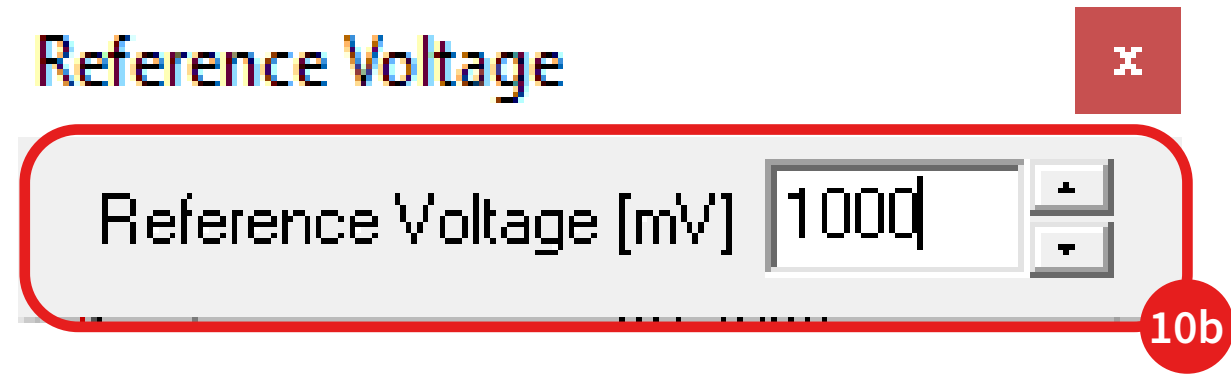
  
  

Noise [pm]	<input type="text" value="0.000"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>
Sudden hops [pm]	<input type="text" value="0.000"/>	<input type="button" value="↑"/> <input type="button" value="↓"/>

**9b** Click to determine the sensitivity ...

**9a** Click to enter the bounds ...

10



10c Get the current wavelength

10a Click to enter the current voltage ...

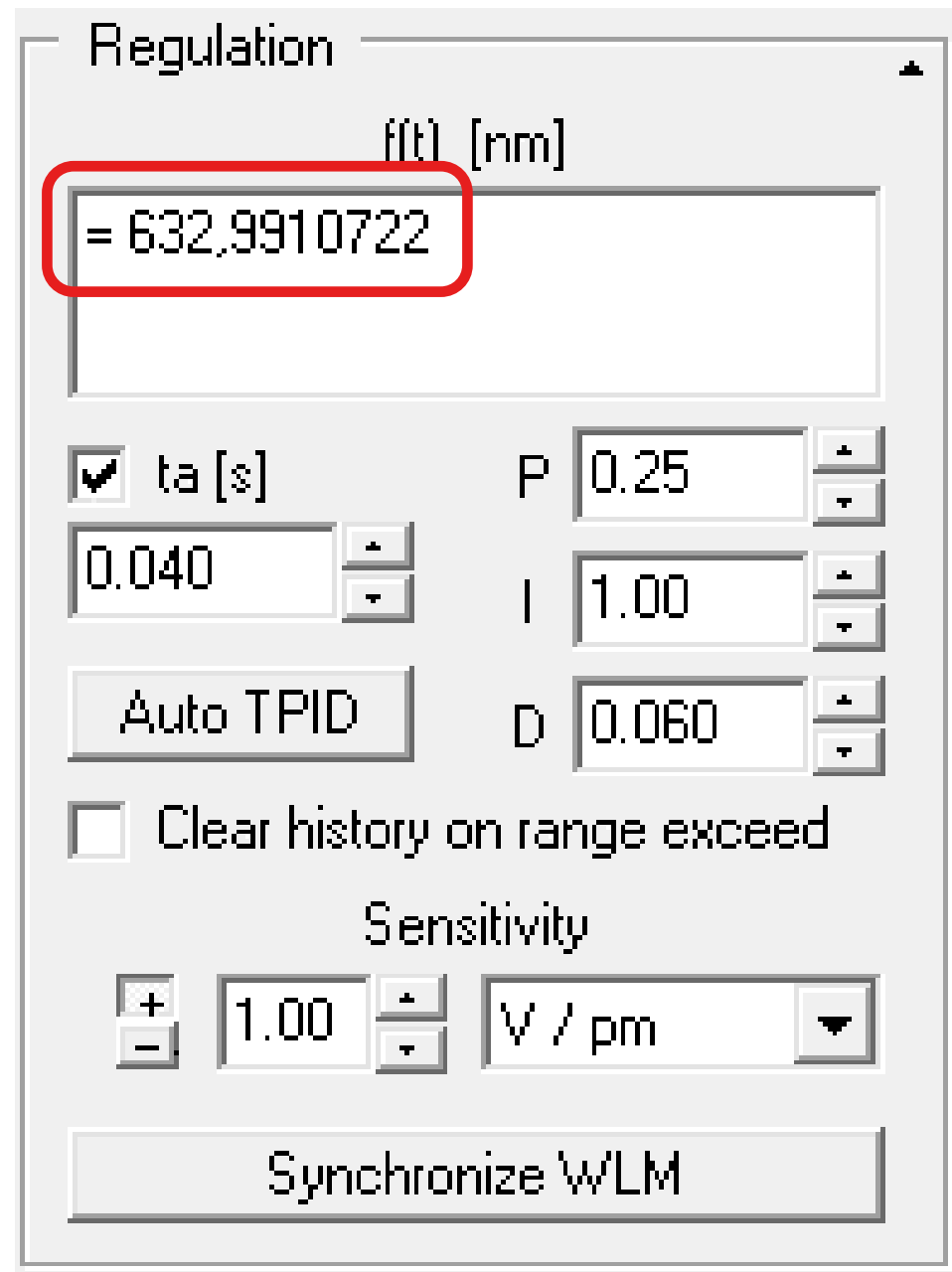
Click on the blue triangle 10a.

Enter the current voltage 10b.

Get the corresponding wavelength by clicking on the red dot 10c.

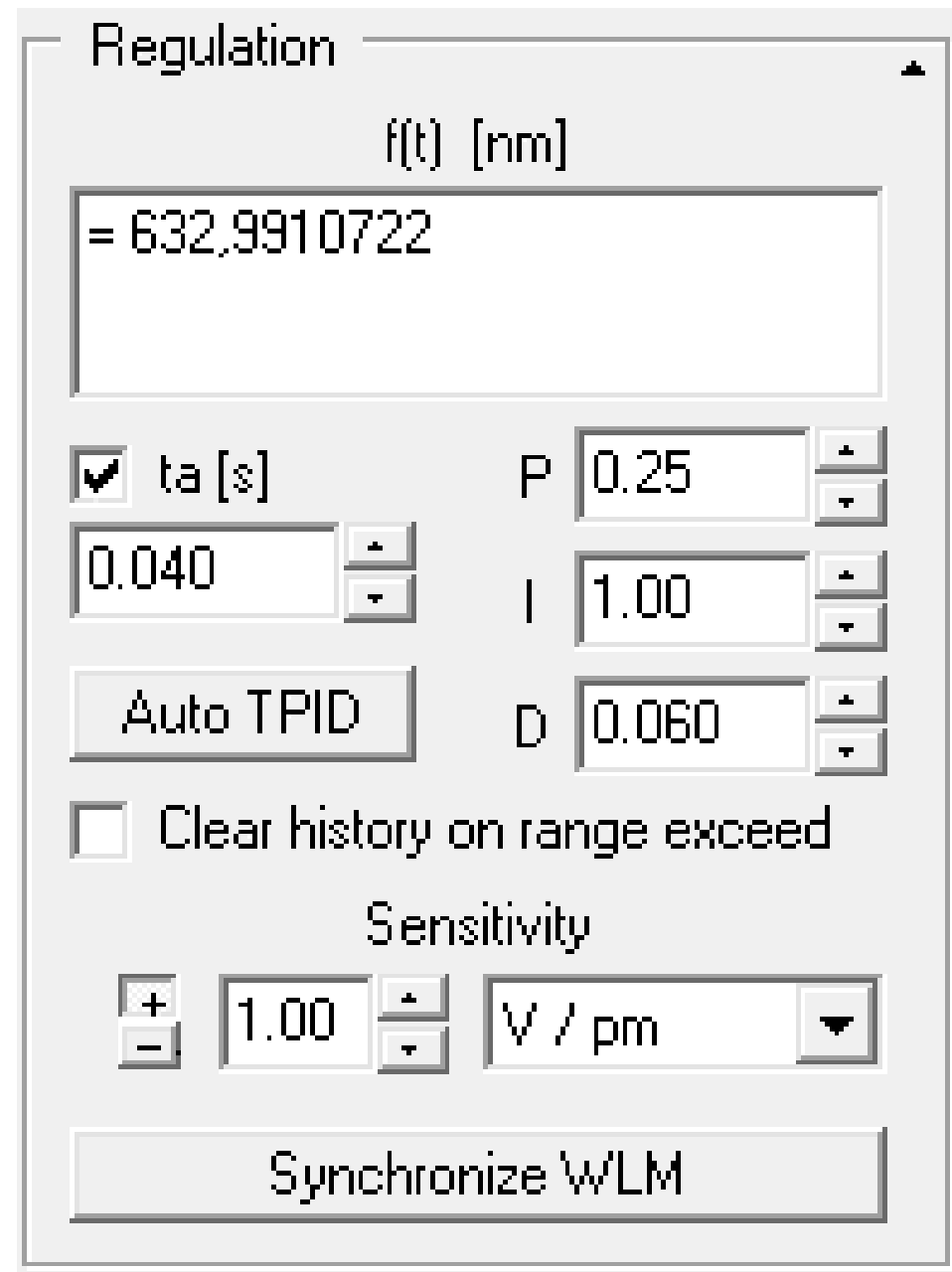


11



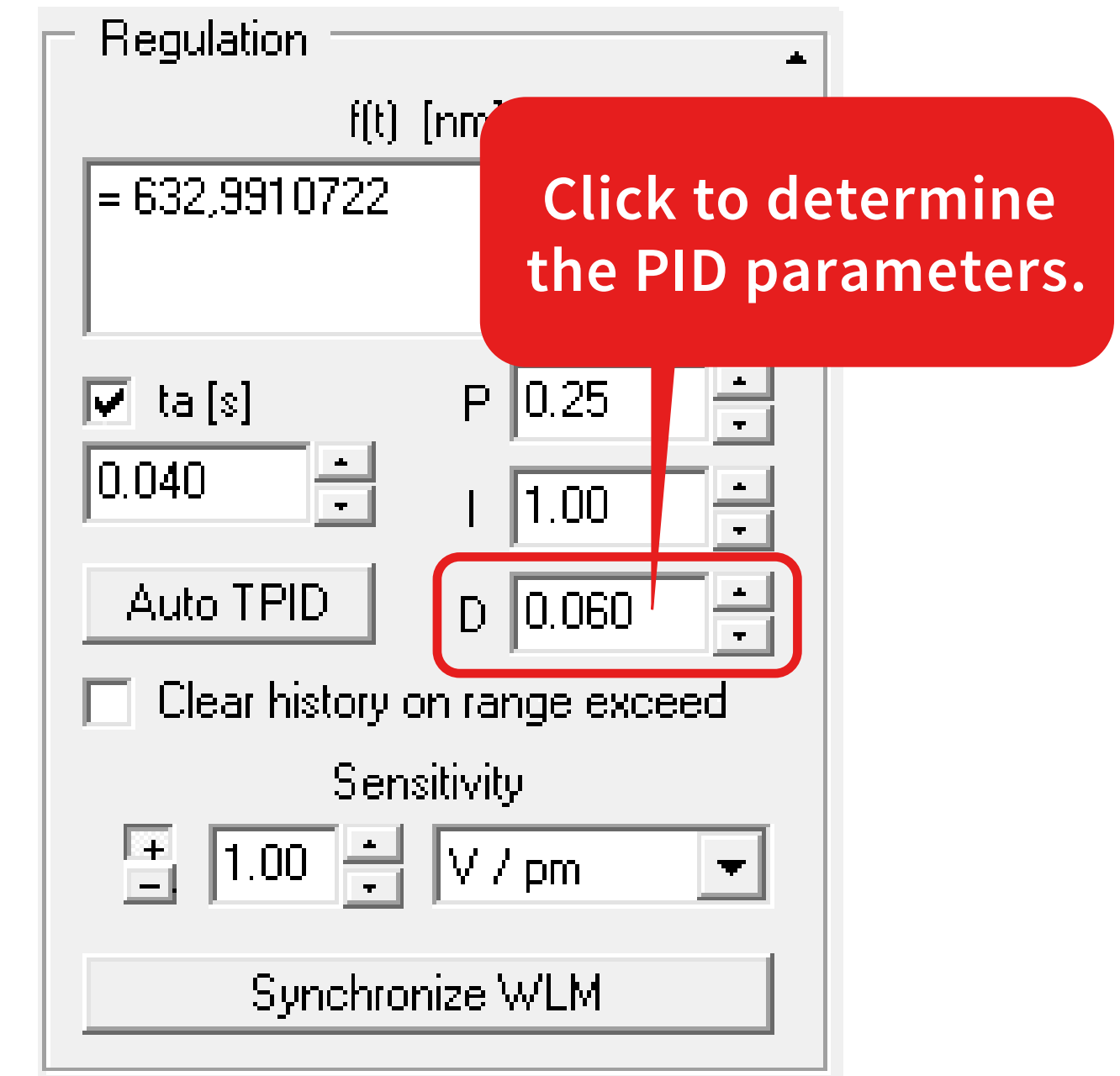
Enter a target wavelength or a function.

11a

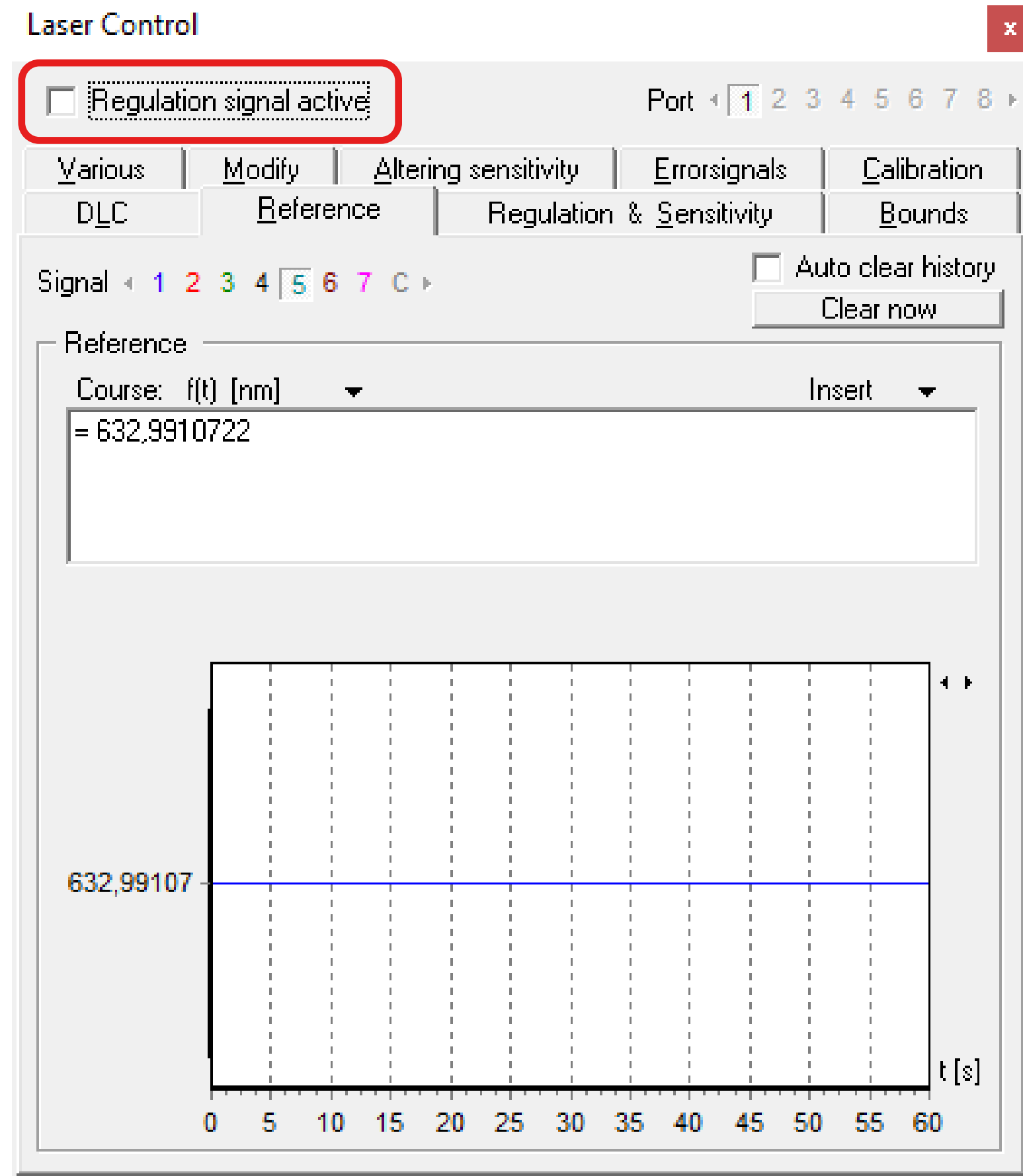


In this example the laser should be stabilized at 632.9910722 nm.

11b

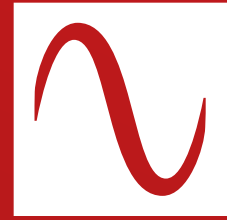


Press "Auto TPID" to determine the PID parameters. Finally, you can close the PIDSIM2. Now the system should be ready for a test.



For this start the Regulation.

You can optimize the regulation further by using the LongTerm application and minimizing possible unwanted effects by altering the PID parameters.



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